Compiler Construction

Intermediate Representation

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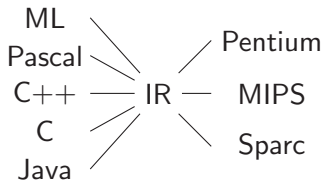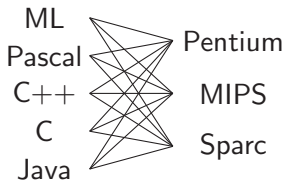
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Outline
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We could go directly from the AST to machine code, but ...

Intermediate representation

- front end: lexical analysis, parsing, semantic analysis
- back end: machine specific optimization, translation to machine language
- intermediate code: machine and language independent optimization

Specifics of Intermediate Representation

A good IR is

- convenient to produce from AST
- convenient to translate into machine language
- small, with clear and simple semantics

Main differences: AST vs. IR

Conditionals if-then-else vs. comparisons and conditional jumps

Method calls various number of arguments vs. simple call ($\rightarrow$ activation frames)

Memory layout array and field deferencing vs. load/store on heap or stack

CONST(i)	integer constant i
NAME(n)	symbolic constant n [code label]
TEMP(t)	temporary t, one of arbitrary many "registers"
BINOP(o,e_1,e_2)	binary operator o with operands e_1 and e_2
MEM(e)	contents of a word of memory at address e
CALL(f,[$e_1, \ldots, e_n$])	procedure call
ESEQ(s,e)	expression sequence; evaluate statement s for side-effects, expression e for result

IR: Statements

MOVE(TEMP(t), e)	Evaluate e and move it into t.
MOVE(MEM (e_1),e_2)	Evaluate e_1 yielding address a; evaluate e_2 and move it into a.
EXP(e)	Evaluate e and discard result.
JUMP(e,[$l_1,\ldots,l_n$])	Transfer control (jump) to address e; $l_1,\ldots,l_n$ are all possible values for e. Often used: JUMP(l).
CJUMP(o,e_1,e_2,t,f)	Evaluate e_1, then e_2; compare their results using relational operator o. If true, jump to label t, else jump to label f.
SEQ(s_1,s_2)	Statement s_1 followed by statement s_2.
LABEL(n)	Define constant value of name n as current code address. NAME(n) can then be used as targets of jumps, calls, etc.

IR: Operators

Binary arithmetic and logical operators:

PLUS, MINUS, MUL, DIV	integer arithmetic operators
AND, OR, XOR	integer bitwise logical operators
LSHIFT, RSHIFT	integer logical shift operators
ARSHIFT	integer arithmetic right-shift

Relational operators:

EQ, NE	integer equality and non-equality (signed or unsigned)
LT, GT, LE, GE	integer inequalities (signed)
ULT, UGT, ULE, UGE	integer inequalities (unsigned)

Examples
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Translate the following MiniJava statements to IR:

1. `if (x < y) x = y; else x = 0;`
2. `y = z[4];`

1 `if (x < y) x = y; else x = 0;`

- Assume, x corresponds to TEMP 5, y corresponds to TEMP 27.
- Define three (new) label names $L1$, $L2$, and $L3$.

```
CJUMP (LT, TEMP 5, TEMP 27, L1, L2)
L1  MOVE  (TEMP 5, TEMP 27)
JUMP L3
L2  MOVE  (TEMP 5, CONST 0)
L3  ...
```

2 `y = z[4];`

- Assume y corresponds to TEMP 27, and the array z is at memory location MEM a.
- Let w be the word size of MiniJava (e.g. 4 bytes).
- Calculate the offset for array index i.

```
MOVE (TEMP 27, +(MEM a, *(CONST 4, CONST w)))
```

Here, we use o(e1,e2) as abbreviation for BINOP(o,e1,e2).

Registers store local variables and temporary results; pass parameters and return results (for function calls), depending on the architecture's calling conventions.

Heap area of memory used for dynamic memory allocation (e.g. arrays, objects)

Stack frames maintained in program's virtual address space

Non-local data can be either referenced via static links to stack locations (also as local data of other frames), or to heap locations.

stack	*high address*
free memory	
heap	
static data	
code	*low address*

Stack frames
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incoming arguments	argument n
	...
	argument 2
	argument 1
frame pointer →	static link

previous frame

	local variables
	return address
	temporaries
	saved registers

current frame

outgoing arguments	argument m
	...
	argument 2
	argument 1
stack pointer →	static link

next frame

↓ *lower address*

The following actions are divided between the caller and the callee:

1. Evaluates actual arguments and puts values on the top of the caller's SF.

2. Stores return address in caller's SF (sometimes in the callee's SF).

3. Stores the caller's frame pointer register in callee's SF.

4. Modifies the frame pointer fp, making it point to callee's SF.

5. Modifies the stack pointer sp, making it point to the to top of the stack.

6. Go to callee's first instruction.

7. Callee begins execution.

1. Caller needs to retrieve the function return value.
2. Restores saved stack pointer for caller.
3. Restores saved register contents for caller.
4. Return to the caller.

- Modern machines have a large set of registers (typically 32 registers).
- Register access is faster than memory loads and stores.
- Most functions have few parameters. Therefore, use small number of registers to pass parameters. The rest of the parameters, if any, can be passed in the stack.
- Returning function's results through registers.
- Caller-safe registers: caller is responsible to save and restore register contents.
- Callee-safe registers: callee is responsible to save and restore register contents.
- Convention is described in machine architecture manual.

- Variables passed by reference need to have a memory address ($\rightarrow$ escaping vars).
- Variables accessed by a procedure nested inside the current one.
- Values which are too big to fit into a single register.
- Variable is an array ($\rightarrow$ address arithmetic).
- Register holding the variable is needed for specific purpose.
- There are too many local variables and temporary values to fit all in registers ($\rightarrow$ spilling).

Pointers/References

- Size is given by the natural word size of the given machine architecture.

Basic data types

- Integers are scalar, i.e. they occupy one word each.
- Boolean false is represented as 0, true by every non-zero value (e.g. 1).
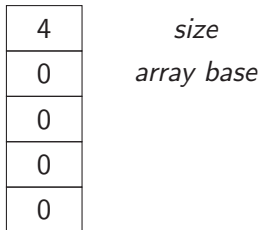- Other data types may be padded.

Strings

- Typically implemented statically at constant address of a segment of memory.
- In Java byte code, strings are collectively put into the constant pool.
- In assembly language, referred to by a label.
- PASCAL: fixed-length arrays of characters
- C: zero-terminated array of characters, variable length

Arrays (one-dimensional)

1. Size: reserve one word for the size of the array.
2. Entries: reserve space for entry of the array.

E.g. `new int[4]`

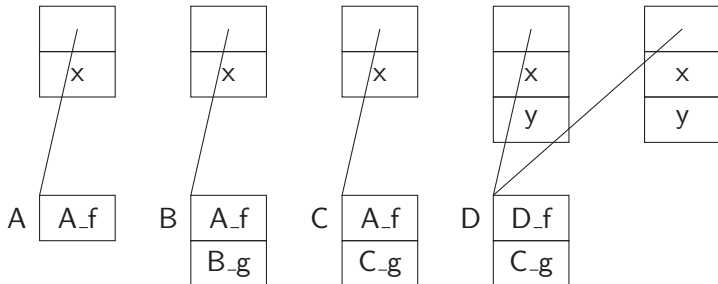|	
4	*size*
0	*array base*
0	
0	
0	

Objects

1. Methods: pointer to the *vtable* (virtual method table) of the corresponding class.
2. Fields: reserve space for fields of the class and for fields of the super classes

For OO languages with single-inheritance, a *prefixing* technique is used.

```
1  class A            {int x = 0; int f() {...} }
2  class B extends A {int g() {...} }
3  class C extends B {int g() {...} }
4  class D extends C {int y = 0; int f() {...} }
```

Using Expressions in different Contexts

Compare the translation for `x > 3` in

- `y = x > 3;`
- `if (x > 3) s1 else s2`

In C-like languages, what about `x = 3` in

- `x = 3;`
- `if (x = 3) s1 else s2`

Idea

Distinguish between different **contexts** of usage!

Contexts

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Key ideas

You have an expression and want to use it as

- an expression: no problem
- a statement: `new EXP(...)`
- a conditional branch: create branch instruction with test against 0

You have a statement and want to use it as ...

- in MiniJava only as statement!

ExCtx(exp) context where a value is required

NxCtx(stm) context where no value is required

CxCtx context with condition (abstract)

RelCxCtx(op,left,right) relational operations

IfThenElseCtx context of if-then-else construct

We will keep the approach here a bit more general as there might be other kinds of ASTs. Conversion operations allow to use a form in the context of another :

> unEx converts to IR expression that evaluates inner tree and returns its value
>
> unNx converts to IR statement that evaluates inner tree but returns no value
>
> unCx(t,f) converts to IR statement that evaluates inner tree and branches to true destination if non-zero, to false destination otherwise

Simple variables For now, we declare them as temporaries

ExCtx(TEMP t)

Arithmetic operations Choose the right binary operation!

a op b $\rightarrow$ ExCtx(BINOP (op,a.unEx,b.unEx))

Unary operations are translated with a trick:

- negation of integers $\rightarrow$ subtraction from zero
- unary complement $\rightarrow$ XOR with all ones

Array elements Arrays are allocated on the heap.

$$e[i] \rightarrow \text{ExCtx(MEM (ADD(e.unEx(),}$$
$$\text{MUL(i.unEx(), CONST w))))}$$

Here, w is the target machine's word size.

In MiniJava, all values are word-sized.

Array bounds check: Check that array index i is between 0 and e.size. To this end, we will save the size in the word preceding the base.

Object fields Objects are allocated on the heap.

$$e.f \rightarrow \text{ExCtx(MEM (ADD(e.unEx(), CONST o)))}$$

where o is the byte offset of field f in the object.

Null pointer check: Check that object expression is non-null.

Array allocation Arrays are allocated on the heap.

- Call external memory allocation function with needed size.
- Add size of array in the first memory chunk.
- Initialize then all fields with default values.
- Return address of first field as base of array.

Object allocation Objects are allocated on the heap.

- In constructor, call first external memory allocation function with needed size.
- Initialize pointer to the corresponding vtable (virtual method table).
- Initialize then all fields with default values.
- Return address of first field as base of object.

Method call In OO language, `this` is an implicit variable. The pointer of the calling object will be added as parameter to each function!

- Fetch the class descriptor at offset 0 from object c.
- Fetch the method-instance pointer p from the (constant) offset f.
- Call p.

```
ExCtx(CALL(MEM( +(MEM(-(e0.unEx(), CONST(w)),
*(m.index ,CONST(w)))),
e0.unEx(),e1.unEx(),...,en.unEx())))
```

Null pointer check: Check that object expression is non-null. For static methods, the function label/address can be done at compile time.

Code is structured into *basic blocks*:

- a maximal sequence of instructions without branches (straight-line code)
- a label starts a new basic block

For implementing control structures:

- Link up the basic blocks!
- Implementation requires bookkeeping (labels!).

```
while(c) s
```

- evaluate *c*
- if true, jump to loop body, else jump to next statement after loop
- evaluate loop body *s*
- jump to conditional
- if true, jump back to loop body

```
NxCtx(SEQ( SEQ(
LABEL(cond), c.unCx(body,done)),
SEQ( SEQ(
LABEL(body), SEQ(s.unNx(),JUMP(cond)))),
LABEL(done)))
```

```
for(i, c, u) s
```

- evaluate initialization statement *i*
- evaluate *c*
- if true, jump to loop body, else jump to next statement after loop
- evaluate loop body *s*
- evaluate update statement *u*
- jump to condition statement

```
NxCtx(SEQ( i.unNx(),
SEQ(SEQ(
LABEL(cond),c.unCx(body,done)),
SEQ(SEQ(
LABEL(body), SEQ(s.unNx(),SEQ(u.unNx(),
JUMP(cond)))),
LABEL(done)))))
```

- when translating a loop, push the done label on some stack
- `break` simply jumps to label on top of stack
- when done with translating the loop and its body, pop the label from the stack

case E of V_1: S_1 ... V_n: S_n end

- evaluate the expression
- find value in case list equal to value of expression
- execute statement associated with value found
- jump to next statement after case

Key issue: finding the right case!

- sequence of conditional jumps (small case set): $O(|cases|)$
- binary search of an ordered jump table (sparse case set): $O(\log_2 |cases|)$
- hash table (dense case set): $O(1)$

```
          evaluate E into t
          if t != V₁ jump L₁
          code for S₁
          jump next
L₁:       if t != V₂ jump L₂
          code for S₂
          jump next
. . .
Lₙ₋₁:     if t != Vₙ jump Lₙ
          code for Sₙ
          jump next
Lₙ:       code to raise run-time exception
next:
```

```
          evaluate E into t
          jump test
L₁:       code for S₁
          jump next
L₂:       code for S₂
          jump next
. . .
Lₙ:       code for Sₙ
          jump next
test:     if t = V₁ jump L₁
          if t = V₂ jump L₂
. . .
          if t = Vₙ jump Lₙ
          code to raise run-time exception
next:
```

Array allocation

- constant bounds:
    - allocate in static area, stack, or heap
    - no run-time descriptor is needed
- dynamic arrays: bounds fixed at run-time
    - allocate in stack or heap
    - descriptor is needed
- dynamic arrays: bounds can change at run-time
    - allocate in heap
    - descriptor is needed

Array layout

- Contiguous:
    - Row major: Rightmost subscript varies most quickly

      ```
      A[1,1], A[1,2], ...
      A[2,1], A[2,2], ...
      ```

      Used in PL/1, Algol, Pascal, C, Ada, Modula, Modula-2, Modula-3
    - Column major: Leftmost subscript varies most quickly

      ```
      A[1,1], A[2,1], ...
      A[1,2], A[2,2], ...
      ```

      Used in FORTRAN
- By vectors:
    - Contiguous vector of pointers to (non-contiguous) subarrays

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Implementation
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```
1  interface Ctx {
2    Exp unEx();
3    Stm unNx();
4    Stm unCx(Label t, Label f);
5  }
```

```
1  class ExCtx implements Ctx {
2    Exp exp;
3    ExCtx (Exp e)    {exp = e;}
4    Exp unEx()       {return exp;}
5    Stm unNx()       {return new EXP(exp);}
6    Stm unCx(Label t, Label f)
7    { ... ? ... } // homework ;)
8  }
```

```
1   class NxCtx implements Ctx {
2     Stm stm;
3     NxCtx (Stm s)    {stm = s;}
4     Exp unEx()       { ... ? ... } // never
          needed in MiniJava
5     Stm unNx()       {return stm;}
6     Stm unCx(Label t, Label f)
7     { ... ? ... } // never needed in MiniJava
8   }
```

```
1   abstract class CxCtx implements Ctx {
2     Exp unEx()        { ... ? ... }  // next
          slide
3     Stm unNx()        { ... ? ... }  // homework
          ;)
4     abstract Stm unCx(Label t, Label f);
5   }
```

```
1   abstract class CxCtx implements Ctx {
2     Exp unEx() {
3       Temp r  = new Temp();
4       Label t = new Label();
5       Label f = new Label();
6       return ESEQ(
7       SEQ( MOVE (TEMP(r), CONST(1)),
8       SEQ( this.unCx(t,f),
9       SEQ( LABEL(f),
10      SEQ( MOVE (TEMP(r), CONST(0)),
11      LABEL(t))))),
12      TEMP(r)));
13    }
14    Stm unNx()         { ... ? ... }  // homework
         ;)
15    abstract Stm unCx(Label t, Label f);
16  }
```

Implementation

For comparisons (e.g. x < 5):

```
1  class RelCxCtx extends CxCtx {
2    RelOp o; Exp left; Exp right;
3    RelCxCtx (RelOp o, Exp left, Exp right )
         {...}
4    Stm unCx(Label t, Label f) {
5      return CJUMP(o,left,right,t,f);
6    }
7  }
```

Translate short-circuiting boolean operators as if they were conditionals. May use if-then-else construct/conditional expression $e_1?e_2 : e_3$.

Example

`x < 5 && y > 0` is treated as

$$(x < 5) ? (y > 0) : 0$$

We translate $e_1?e_2 : e_3$ into an IfThenElseCtx(e_1,e_2,e_3) :

```
1   class IfThenElseCtx implements Ctx{
2     Exp e1; Exp e2; Exp e3;
3     IfThenElseCtx (Exp e1, Exp e2, Exp e3)
4     {this.e1 = e1; this.e2 = e2; this.e3 = e3;}
5     Exp unEx()      { ... ? ... }
6     Stm unNx()      { ... ? ... }
7     Stm unCx(Label t, Label f)
8     { ... ? ... }
```

When using a IfThenElseCtx as an expression:

```
1   Exp unEx(){
2     Label t = new Label();
3     Label f = new Label();
4     Temp  r = new Temp();
5     return ESEQ(
6     SEQ( e1.unCx(t,f),
7     SEQ( SEQ (LABEL (t),
8     SEQ( MOVE ( TEMP(r), e2.unEx()),
9     JUMP (j))),
10    SEQ ( LABEL(f), SEQ( MOVE (TEMP(r), e3.unEx
          ()),
11    JUMP (j)))),
12    LABEL(j)),
13    TEMP (r));
14    }
```

When using a IfThenElseCtx as a conditional:

```
1   Stm unCx(Label t, Label f) {
2     Label tt = new Label();
3     Label ff = new Label();
4     return SEQ ( e1.unCx(tt,ff),
5     SEQ(SEQ (LABEL(tt),e2.unCx(t,f)),
6     SEQ(LABEL(ff), e3.unCx(t,f))));
7   }
```

Mismatches between IR and machine code

- Evaluation order of `ESEQ`'s within expressions must be made explicit, same for `CALL` nodes.
- `CALL` nodes at argument expression of other `CALL`s cause problems with registers.
- `CJUMP` may jump to either of two labels, conditional jumps of machines "fall through" if condition is false.

Idea

Yet another tree re-writing step!

- Eliminate SEQ and ESEQ nodes ⇒ simple list of statements!
- CALL can only be subtree of EXP(...) or MOVE(TEMP t,...).
- Group sequences into basic blocks without internal jumps or labels.
- Arrange basic blocks where every CJUMP is followed by false branch.

ESEQ
s_1 ESEQ
s_2 e

ESEQ
SEQ e
s_1 s_2

$$\text{ESEQ}(s_1, \text{ESEQ}(s_2, e)) \Rightarrow \text{ESEQ}(\text{SEQ}(s_1, s_2), e)$$

$$\text{BINOP(op, ESEQ}(s,e_1),e_2) \Rightarrow \text{ESEQ}(s,\text{BINOP(op},e_1,e_2))$$
$$\text{MEM(ESEQ}(s,e_1)) \Rightarrow \text{ESEQ}(s,\text{MEM}(e_1))$$
$$\text{JUMP(ESEQ}(s,e_1)) \Rightarrow \text{ESEQ}(s,\text{JUMP}(e_1))$$
$$\text{CJUMP(op,ESEQ}(s,e_1),e_2,l_1,l_2) \Rightarrow \text{SEQ}(s,\text{CJUMP(op},e_1,e_2,l_1,l_2))$$

$$\text{BINOP(op, } e_1,\text{ESEQ}(s,e_2)) \Rightarrow \text{ESEQ(MOVE(TEMP t},e_1),\\ \text{ESEQ}(s,\\ \text{BINOP(op,TEMP t},e_2)))$$

$$\text{CJUMP(op,}e_1,\text{ESEQ}(s,e_2),l_1,l_2) \Rightarrow \text{SEQ(MOVE(TEMP t},e_1),\\ \text{SEQ(s,}\\ \text{CJUMP(op,TEMP t},e_2,l_1,l_2)))$$

If s and e_1 commute, we can optimize:

$$BINOP(op, e_1, ESEQ(s,e_2)) \Rightarrow ESEQ(s, BINOP(op, e_1, e_2))$$
$$CJUMP(op, e_1, ESEQ(s,e_2), l_1, l_2) \Rightarrow SEQ(s, CJUMP(op, e_1, e_2, l_1, l_2))$$

Example

- MOVE(MEM(x),y) commutes with MEM(z) iff $x \neq z$.
- Any statement commutes with CONST(n).

From the examples so far, we can derive this somewhat general approach:

- Extract recursively all ESEQ's out of all subexpressions.
- Generate statement sequences where sub-expressions are evaluated into temporaries.
- Rebuild original construct.

Use similar technique to eliminate nested function calls:

$$CALL(f, args) \Rightarrow ESEQ(MOVE(TEMP\ t, CALL(f, args)), TEMP\ t)$$

A basic block

- starts with a LABEL,
- end with a JUMP or CJUMP, and
- there are no other LABELs, JUMPs, or CJUMPs

A trace

- is a sequence of statements that could be consecutively executed in the program.

Arrange the blocks to get "optimal" traces!

- Divide the list of statements of a function body into blocks.
- Put all the blocks into a list Q.
- While Q is not empty:
    - Start new (empty) trace T.
    - Remove head element b from Q.
    - While b is not marked:
        - Mark b.
        - Append b to the end of the current trace T.
        - Examine the blocks to which b branches:
          If there is any unmarked successor c, let it be the next b.
    - End the current trace T.

- Make sure that every CJUMP is followed by its false label.
    - If followed by true label, negate condition and swap labels.
    - If followed by neither label, insert dummy label f' and jump.

```
CJUMP(cond,a,b,t,f')
LABEL f'
JUMP(NAME f)
```

- Remove jumps that are immediately followed by their target label.

prologue statements	*prologue statements*	*prologue statements*
~~JUMP(NAME(test))~~	~~JUMP(NAME(test))~~	JUMP(NAME test)
LABEL(test)	LABEL(test)	LABEL(body)
CJUMP($>$,i, N,done,body)	CJUMP($\leq$,i, N,body,done)	*loop body statements*
LABEL(body)	LABEL(done)	~~JUMP(NAME(test))~~
loop body statements	*epilogue statements*	LABEL(test)
JUMP(NAME test)	LABEL(body)	CJUMP($\leq$,i, N,body,done)
LABEL(done)	*loop body statements*	LABEL(done)
epilogue statements	JUMP(NAME test)	*epilogue statements*

Alternative Intermediate Representations

- Directed acyclic graphs (DAGs): identifies common subexpression
- Three-address code: at most one operator at the right side of an instruction
- Static single assignment form (SSA): all assignments are to variables with distinct names