

Principles of Programming Languages

Lecture 08 Modules

Albert-Ludwigs-Universität Freiburg

Gabriel Radanne

University of Freiburg, Germany

radanne@informatik.uni-freiburg.de

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- Modules
 - Abstract data type packaged with operators.
 - Can import other (known) modules.
 - Can be parameterized with (unknown) modules.
- Parametric modules
 - Functions over existential types.

Example: Module with two Implementations

```
type PointWRT[PointRep] =  
  {mkPoint: (Real × Real) → PointRep,  
   x_coord: PointRep → Real,  
   y_coord: PointRep → Real}  
  
type Point = ∃ PointRep. PointWRT[PointRep]  
  
value cartesianPointOps =  
  {mkpoint = fun(x: Real, y: Real) (x,y),  
   x_coord = fun(p: Real × Real) fst(p),  
   y_coord = fun(p: Real × Real) snd(p)}  
  
value cartesianPointPackage: Point =  
  pack[PointRep = Real × Real in PointWRT[PointRep]]  
    (cartesianPointOps)  
  
value polarPointPackage: Point =  
  pack[PointRep = Real × Real in PointWRT[PointRep]]  
    {mkpoint = fun(x: Real, y: Real) ... ,  
     x_coord = fun(p: Real × Real) ... ,  
     y_coord = fun(p: Real × Real) ... }
```

```
type ExtendedPointWRT [PointRep] =  
  PointWRT [PointRep] &  
  {add: (PointRep × PointRep) → PointRep}  
  
type ExtendedPoint =  
  ∃ PointRep. ExtendedPointWRT [PointRep]  
  
value extendPointPackage =  
  fun(pointPackage: Point)  
  open pointPackage as p [PointRep] in  
    pack [PointRep ' = PointRep in ExtendedPointWRT [PointRep ']]  
    p & {add = fun(a: PointRep, b: PointRep)  
          p.mkpoint(p.x_coord(a)+p.x_coord(b),  
                   p.y_coord(a)+p.y_coord(b))}  
  
value extendedCartesianPointPackage =  
  extendPointPackage(cartesianPointPackage)
```



A Circle Package

```
type CircleWRT2[CircleRep, PointRep] =  
  {pointPackage: PointWRT[PointRep],  
   mkcircle: (PointRep × Real) → CircleRep,  
   center: CircleRep → PointRep, ... }  
  
type CircleWRT1[PointRep] =  
  ∃ CircleRep. CircleWRT2[CircleRep, PointRep]  
  
type Circle =  
  ∃ PointRep. CircleWRT1[PointRep]  
  
type CircleModule =  
  ∀ PointRep.  
  PointWRT[PointRep] → CircleWRT1[PointRep]  
  
value circleModule: CircleModule =  
  all[PointRep]  
    fun(p: PointWRT[PointRep])  
      pack[CircleRep = PointRep × Real  
        in CircleWRT2[CircleRep, PointRep]]  
      {pointPackage = p,  
       mkcircle = fun(m: PointRep, r: Real)(m, r) ... }  
  
value cartesianCirclePackage =  
  open CartesianPointPackage as p[Rep] in  
  pack[PointRep = Rep in CircleWRT1[PointRep]]  
  circleModule[Rep](p)  
  
open cartesianCirclePackage as c0[PointRep] in  
open c0 as c[CircleRep] in  
  ... c.mkcircle(c.pointPackage.mkpoint(3, 4), 5) ...
```

A Rectangle Package

```
type RectWRT2[RectRep, PointRep] =  
  {pointPackage: PointWRT[PointRep],  
   mkrect: (PointRep × PointRep) → RectRep, ... }  
  
type RectWRT1[PointRep] =  
  ∃ RectRep. RectWRT2[RectRep, PointRep]  
  
type Rect =  
  ∃ PointRep. RectWRT1[PointRep]  
  
type RectModule = ∀ PointRep.  
  PointWRT[PointRep] → RectWRT1[PointRep]  
  
value rectModule: RectModule =  
  all[PointRep]  
    fun(p: PointWRT[PointRep])  
      pack[PointRep' = PointRep  
        in RectWRT1[PointRep']]  
      {pointPackage = p,  
       mkrect = fun(tl: PointRep, br: PointRep) ... }
```



A Figures Package

```
type FiguresWRT3[RectRep, CircleRep, PointRep] =  
  {circlePackage: CircleWRT[CircleRep, PointRep],  
   rectPackage: RectWRT[RectRep, PointRep],  
   boundingRect: CircleRep → RectRep}  
  
type FiguresWRT1[PointRep] =  
  ∃ RectRep. ∃ CircleRep.  
    FiguresWRT3[RectRep, CircleRep, PointRep]  
  
type Figures =  
  ∃ PointRep. FiguresWRT1[PointRep]  
  
type FiguresModule = ∀ PointRep.  
  PointWRT[PointRep] → FiguresWRT1[PointRep]  
  
value figuresModule: FiguresModule =  
  all[PointRep]  
    fun(p: PointWRT[PointRep])  
      pack[PointRep' = PointRep  
        in FiguresWRT1[PointRep]]  
      open circleModule[PointRep](p) as c[CircleRep] in  
        open rectModule[PointRep](p) as r[RectRep] in  
          {circlePackage = c, ... }
```

This is a *low-level* view of modules. Let's take a step back to more familiar grounds.

This is a *low-level* view of modules. Let's take a step back to more familiar grounds. There are as many module systems as there are programming languages.



Modules in C?

No notion of modules in C or C++.

Namespacing is done by prefixes, imports are done with `include`.

```
#include <stdlib.h>
```

```
int package_function ( ... );
```

- No encapsulation
- Separate compilation doesn't really work
- Order/dependencies doesn't matter but you can make the preprocessor loop.

- *packages* provides namespacing, imports and separate compilation
- *classes* provides encapsulation
- Rich class language (interfaces, inheritance, generics, ...)
- No cycles!

```
import java.util.ArrayList;
```

```
public class Algo {  
    public int thing;  
    private int hidden;  
    protected int local;  
  
    public int do_thing ( ... ) {  
        ...  
    }  
}
```

Recent extension (Ecmascript 6).

```
import * as lib from 'lib';  
  
export function dothing() {  
  ...  
}  
  
export { foo as myFoo, bar } from 'src/other_module';
```

- Namespacing and imports
- Little bit of encapsulation (can hide functions)
- Can make cycles

Rust has a proper notion of modules

- Namespacing and imports
- Encapsulations for type and functions
- Rich manipulation of modules (can open and rebind them, pointed access, ...)

```
pub mod network {  
    pub fn connect() { ... }  
    fn internal_fun() { ... }  
    pub mod server { ... }  
}
```

```
use network;
```

```
fn main() {  
    server::thing()  
}
```

What we expect from a module system



- Structuring programs

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 - Cut programs in smaller, easier to manage, pieces

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 - Cut programs in smaller, easier to manage, pieces
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Additional worthwhile goals:

- Genericity: Modules that are parameterized by other modules

What we expect from a module system



- Structuring programs
 - Cut programs in smaller, easier to manage, pieces
 - Manage dependencies
- Modularity: Make smaller pieces of program compose.
- Encapsulation: Hide the implementation details of a module to the outside words.

Additional worthwhile goals:

- Genericity: Modules that are parameterized by other modules
- Extended modularity: Separate compilation



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Demo!

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Module Expressions

$M ::= X_i \mid p.X$ (Variables)
| $(M:\mathcal{M})$ (Type constraint)
| $M_1(M_2)$ (Functor application)
| **functor** $(X_i:\mathcal{M})M$ (Functor)
| **struct** S **end** (Structure)

Structure body

$S ::= \varepsilon \mid D; S$

Structure components

$D ::= \text{let } x_i = e$ (Values)
| **type** $t_i = \tau$ (Types)
| **module** $X_i = M$ (Modules)

Programs

$P ::= \text{prog } S \text{ end}$

Module types

$\mathcal{M} ::= \text{sig } \mathcal{S} \text{ end}$ (Signature)
| $\text{functor}(X_i : \mathcal{M}_1)\mathcal{M}_2$ (Functor)

Signature body

$\mathcal{S} ::= \varepsilon \mid \mathcal{D}; \mathcal{S}$

Signature components

$\mathcal{D} ::= \text{val } x_i : \tau$ (Values)
| $\text{type } t_i = \tau$ (Types)
| $\text{type } t_i$ (Abstract types)
| $\text{module } X_i : \mathcal{M}$ (Modules)

Modules

$V ::= V_b^*$ (Structure)
| $\text{functor}(\rho)(X_i : \mathcal{M})M$ (Closures)

Bindings

$V_b ::= \{x_i \mapsto v\}$ (Values)
| $\{X_i \mapsto V\}$ (Modules)

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ValDecl

$$\frac{e \xrightarrow{\rho} v \quad S \xrightarrow{\rho + \{x_i \mapsto v\}} V_s}{(\text{let } x_i = e; S) \xrightarrow{\rho} \{x_i \mapsto v\} + V_s}$$

ValDecl

$$\frac{e \xrightarrow{\rho} v \quad S \xrightarrow{\rho + \{x_i \mapsto v\}} V_s}{(\text{let } x_i = e; S) \xrightarrow{\rho} \{x_i \mapsto v\} + V_s}$$

TypeDecl

$$\frac{S \xrightarrow{\rho} V_s}{(\text{type } t_i = \tau; S) \xrightarrow{\rho} V_s}$$

ModuleDecl

$$\frac{M \xrightarrow{\rho} V \quad S \xrightarrow{\rho + \{X_i \mapsto V\}} V_s}{(\text{module } X_i = M; S) \xrightarrow{\rho} \{X_i \mapsto V\} + V_s}$$

$$\text{ValDecl} \quad \frac{e \xrightarrow{\rho} v \quad S \xrightarrow{\rho + \{x_i \mapsto v\}} V_s}{(\text{let } x_i = e; S) \xrightarrow{\rho} \{x_i \mapsto v\} + V_s}$$

$$\text{TypeDecl} \quad \frac{S \xrightarrow{\rho} V_s}{(\text{type } t_i = \tau; S) \xrightarrow{\rho} V_s}$$

$$\text{ModuleDecl} \quad \frac{M \xrightarrow{\rho} V \quad S \xrightarrow{\rho + \{X_i \mapsto V\}} V_s}{(\text{module } X_i = M; S) \xrightarrow{\rho} \{X_i \mapsto V\} + V_s}$$

$$\text{Struct} \quad \frac{S \xrightarrow{\rho} V_s}{(\text{struct } S \text{ end}) \xrightarrow{\rho} V_s}$$

$$\text{EmptyStruct} \quad \frac{}{\varepsilon \xrightarrow{\rho} \{\}}$$

Reduction rules – Variables and type constraints



$$\text{ModVar} \quad \frac{\rho(X) = V}{X \xRightarrow{\rho} V}$$

$$\text{QualModVar} \quad \frac{p \xRightarrow{\rho} V' \quad V'(X) = V}{p.X \xRightarrow{\rho} V}$$

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$$\text{ModConstr} \frac{M \xRightarrow{\rho} V}{(M : \mathcal{M}) \xRightarrow{\rho} V}$$

ModClosure

$$\frac{}{\text{functor}(X : \mathcal{M})M \xRightarrow{\rho} \text{functor}(\rho)(X : \mathcal{M})M}$$

ModBeta

$$\frac{M \xRightarrow{\rho} \text{functor}(\rho')(X : \mathcal{M})M_f \quad M' \xRightarrow{\rho} V' \quad M_f \xRightarrow{\rho' + \{X \mapsto V'\}} V''}{M(M') \xRightarrow{\rho} V''}$$

Program

$$\frac{S \xRightarrow{\rho} V_s}{\text{prog } S \text{ end} \xRightarrow{\rho} V_s(\text{return})}$$

Example reduction


$$P \equiv \left(\begin{array}{l} \text{prog} \\ \text{module } X = \text{struct let } a = 3 \text{ end} \\ \text{let return} = X.a \\ \text{end} \end{array} \right)$$

Example reduction



$$\begin{array}{c}
 \text{Struct} \quad \frac{\vdots}{\text{let } a = 3 \Rightarrow \{a \mapsto 3\}} \\
 \left(\begin{array}{c} \text{struct} \\ \text{let } a = 3 \\ \text{end} \end{array} \right) \Rightarrow \{a \mapsto 3\} \\
 \text{ModuleDecl} \quad \frac{\text{ModVar} \quad \frac{\rho(X) = V}{X \xrightarrow{\rho} V \equiv \{a \mapsto 3\}} \quad \text{QualModVar} \quad \frac{V(a) = 3}{X.a \xrightarrow{\{X \mapsto \{a \mapsto 3\}\}} 3}}{\text{let return} = X.a \xrightarrow{\{X \mapsto \{a \mapsto 3\}\}} \{\text{return} \mapsto 3\}} \\
 \left(\begin{array}{c} \text{module } X = \text{struct let } a = 3 \text{ end} \\ \text{let return} = X.a \end{array} \right) \Rightarrow \{X \mapsto \{a \mapsto 3\}\} + \{\text{return} \mapsto 3\} \\
 \text{Program} \quad \frac{}{P \Rightarrow 3} \quad \text{Program}
 \end{array}$$

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Two relations:

$\Gamma \triangleright M : \mathcal{M}$: The module M is of type \mathcal{M} in Γ .

$\Gamma \triangleright \mathcal{M} <: \mathcal{M}'$: The module type \mathcal{M} is a subtype of \mathcal{M}' in Γ .

Declarations follow the same flow as the dynamic semantics:

$$\frac{\Gamma \triangleright e : \tau \quad x_i \notin \text{BoundVars}(\Gamma) \quad \Gamma; (\text{val } x_i : \tau) \blacktriangleright S : \mathcal{S}}{\Gamma \blacktriangleright (\text{let } x_i = e; s) : (\text{val } x_i : \tau; \mathcal{S})}$$

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$$\frac{t_i \notin \text{BoundVars}(\Gamma) \quad \Gamma; (\text{type } t_i = \tau) \blacktriangleright S : \mathcal{S}}{\Gamma \blacktriangleright (\text{type } t_i = \tau; s) : (\text{type } t_i = \tau; \mathcal{S})}$$

$$\frac{\Gamma \blacktriangleright M : \mathcal{M} \quad X_i \notin \text{BoundVars}(\Gamma) \quad \Gamma; (\text{module } X_i : \mathcal{M}) \blacktriangleright S : \mathcal{S}}{\Gamma \blacktriangleright (\text{module } X_i = M; s) : (\text{module } X_i : \mathcal{M}; \mathcal{S})}$$

Declarations follow the same flow as the dynamic semantics:

$$\frac{\Gamma \triangleright e : \tau \quad x_i \notin \text{BoundVars}(\Gamma) \quad \Gamma; (\text{val } x_i : \tau) \triangleright S : \mathcal{S}}{\Gamma \triangleright (\text{let } x_i = e; s) : (\text{val } x_i : \tau; \mathcal{S})}$$

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$$\frac{\Gamma \triangleright M : \mathcal{M} \quad X_i \notin \text{BoundVars}(\Gamma) \quad \Gamma; (\text{module } X_i : \mathcal{M}) \triangleright S : \mathcal{S}}{\Gamma \triangleright (\text{module } X_i = M; s) : (\text{module } X_i : \mathcal{M}; \mathcal{S})}$$

$$\frac{\Gamma \triangleright S : \mathcal{S}}{\Gamma \triangleright \text{struct } S \text{ end} : \text{sig } \mathcal{S} \text{ end}}$$

$$\frac{}{\Gamma \triangleright \varepsilon : \varepsilon}$$

Normal variables are typechecked as usual, but *qualified* variables are surprisingly complicated.

$$\frac{\text{ModVar} \\ (\text{module } X_i : \mathcal{M}) \in \Gamma}{\Gamma \blacktriangleright X_i : \mathcal{M}}$$

$$\frac{\text{QualModVar} \\ \Gamma \blacktriangleright p : (\text{sig } \mathcal{S}_1 ; \text{module } X_i : \mathcal{M} ; \mathcal{S}_2 \text{ end})}{\Gamma \blacktriangleright p.X : \mathcal{M}[n_i \mapsto p.n \mid n_i \in \text{BoundVars}(\mathcal{S}_1)]}$$

Type checking – Variables – Example



An example of type checking for qualified accesses. Given the module X , we wish to typecheck $X.a$

```
 $X$  : sig ... type  $t$ ; val  $a$  :  $t$ ; ... end
```

Type checking – Variables – Example

An example of type checking for qualified accesses. Given the module X , we wish to typecheck $X.a$

$$X : \text{sig } \dots \text{ type } t; \text{ val } a : t; \dots \text{ end}$$

We substitute t by $X.t$ in the type of the a with the QualVar rule

$$\text{QualVar} \frac{\text{ModVar} \frac{(\text{module } X : \text{sig } \dots \text{ type } t; \text{ val } a : t; \dots \text{ end}) \in \Gamma}{\Gamma \blacktriangleright X : \text{sig type } t; \text{ val } a : t \text{ end}}}{\Gamma \triangleright X.a : X.t} \text{ with } X.t = t[t \mapsto X.t]$$



```
module Showable : sig
  type t
  val show : t → string
end
module Elt : sig
  type t = Showable.t
  val v : elt
end
```

```
module F
  (E : sig type t val v : t end)
  (S : sig type t = E.t val show : t → string end)
  = struct
    let s = (S.show E.v)
  end
module X = F(Elt)(Showable)
```

“Strengthening” add new type equalities to existing modules

Strength

$$\frac{\Gamma \triangleright p : \mathcal{M}}{\Gamma \triangleright p : \mathcal{M}/p}$$

“Strengthening” add new type equalities to existing modules

$$\begin{array}{l} \text{Strength} \\ \frac{\Gamma \triangleright p : \mathcal{M}}{\Gamma \triangleright p : \mathcal{M}/p} \end{array} \quad \begin{array}{l} \varepsilon/p = \varepsilon \\ (\text{sig } \mathcal{S} \text{ end})/p = \text{sig } \mathcal{S}/p \text{ end} \\ (\text{module } X_i = \mathcal{M}; \mathcal{S})/p = \text{module } X_i = \mathcal{M}/p; \mathcal{S}/p \\ (\text{type } t_i = \tau; \mathcal{S})/p = \text{type } t_i = p.t; \mathcal{S}/p \\ (\text{type } t_i; \mathcal{S})/p = \text{type } t_i = p.t; \mathcal{S}/p \\ (\text{val } x_i : \tau; \mathcal{S})/p = \text{val } x_i : \tau; \mathcal{S}/p \\ (\text{functor}(X_i : \mathcal{M})\mathcal{M}')/p = \text{functor}(X_i : \mathcal{M})(\mathcal{M}'/p(X_i)) \end{array}$$

Functors are typechecked mostly like lambdas:

$$\frac{\Gamma \triangleright M_1 : \text{functor}(X_i : \mathcal{M})\mathcal{M}' \quad \Gamma \triangleright M_2 : \mathcal{M}}{\Gamma \triangleright M_1(M_2) : \mathcal{M}'[X_i \mapsto M_2]}$$

$$\frac{X_i \notin \text{BoundVars}(\Gamma) \quad \Gamma; (\text{module } X_i : \mathcal{M}) \triangleright M : \mathcal{M}'}{\Gamma \triangleright \text{functor}(X_i : \mathcal{M})M : \text{functor}(X_i : \mathcal{M})\mathcal{M}'}$$



Type checking – Module inclusion?

We are not done!

These rules does not allow use to hide fields or to abstract types. We need additional rules for module inclusions:

```
module type S = sig  
  type t  
end
```

```
module X : S = struct  
  type t = int  
  let x = 3  
  (* .. *)  
end
```

Inclusion on type declaration can take many forms:

$$\frac{\Gamma \triangleright \tau_1 \approx \tau_2}{\Gamma \blacktriangleright (\text{type } t_i = \tau_1) <: (\text{type } t_i = \tau_2)}$$

$$\frac{}{\Gamma \blacktriangleright (\text{type } t_i) <: (\text{type } t_i)}$$

$$\frac{\Gamma \triangleright t_i \approx \tau}{\Gamma \blacktriangleright (\text{type } t_i) <: (\text{type } t_i = \tau)}$$

$$\frac{}{\Gamma \blacktriangleright (\text{type } t_i = \tau_1) <: (\text{type } t_i)}$$

This rule allows to take a subset of the fields, and reorder them:

$$\frac{\text{SubStruct} \quad \pi : [1; m] \rightarrow [1; n] \quad \forall i \in [1; m], \Gamma; \mathcal{D}_1; \dots; \mathcal{D}_n \blacktriangleright \mathcal{D}_{\pi(i)} <: \mathcal{D}'_i}{\Gamma \blacktriangleright (\text{sig } \mathcal{D}_1; \dots; \mathcal{D}_n \text{ end}) <: (\text{sig } \mathcal{D}'_1; \dots; \mathcal{D}'_m \text{ end})}$$

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We of course want usual soundness results on modules, but we also want to *prove* encapsulation and modularity.
“encapsulation” and “modularity” are big words without formal meaning. Let’s try to make them more precise



One way to look at modularity: We can typecheck each module without knowing the *implementation* of rest of the program.

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Theorem (Incremental Typechecking)

Given a list of module declarations that form a typed program, there exists an order such that each module can be typechecked with only knowledge of the type of the previous modules.

More formally, given a list of n declarations D_i and a signature S such that

$$\blacktriangleright (D_1; \dots; D_n) : S$$

then there exists n definitions \mathcal{D}_i and a permutation π such that

$$\forall i < n, \mathcal{D}_1; \dots; \mathcal{D}_i \blacktriangleright \mathcal{D}_{i+1} : \mathcal{D}_{i+1} \quad \blacktriangleright \mathcal{D}_{\pi(1)}; \dots; \mathcal{D}_{\pi(n)} <: S$$



Encapsulation means that the if I provide two modules that have the same type, the outside should not be able to differentiate them.

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Theorem (Representation Independence)

Let M_1 and M_2 be two closed module expressions and \mathcal{M} be a module type. Assume that \mathcal{M} is a principal type for M_1 and for M_2 in the empty environment. Then, for all program contexts $C[]$ the program $C[M_1]$ is well-typed if and only if $C[M_2]$ is, and if so, $\llbracket C[M_1] \rrbracket = \llbracket C[M_2] \rrbracket$.

Back to existential and universal types



Modules can be translated into existential packs:

```
type PointWRT[PointRep] =
  {mkPoint: (Real × Real) → PointRep,
   x_coord: PointRep → Real,
   y_coord: PointRep → Real}

type Point = ∃ PointRep. PointWRT[PointRep]

value cartesianPointOps =
  {mkpoint = fun(x: Real, y: Real) (x,y),
   x_coord = fun(p: Real × Real) fst(p),
   y_coord = fun(p: Real × Real) snd(p)}

value cartesianPointPackage: Point =
  pack[PointRep = Real × Real in
    PointWRT[PointRep]] (cartesianPointOps)

value polarPointPackage: Point =
  pack[PointRep = Real × Real in
    PointWRT[PointRep]]
    {mkpoint = fun(x: Real, y: Real) ... ,
     x_coord = fun(p: Real × Real) ... ,
     y_coord = fun(p: Real × Real) ... }
```

```
module type Point = sig
  type t
  val mkPoint : Real × Real → PointRep
  val x_coord: PointRep → Real
  val y_coord: PointRep → Real
end

module cartesianPoint : Point =
  let mkpoint = fun(x: Real, y: Real) (x,y)
  let x_coord = fun(p: Real × Real) fst(p)
  let y_coord = fun(p: Real × Real) snd(p)
end

module polarPoint : Point =
  let mkpoint = fun(x: Real, y: Real) ...
  let x_coord = fun(p: Real × Real) ...
  let y_coord = fun(p: Real × Real) ...
end
```



We have seen that modules as existential and universal-packs can be better expressed using proper module constructs. This can account for encapsulation and modularity, and many additional features such as separate compilation.

We only saw an example of a module language from the ML family. There are many different module systems.